# Multiple Access Channel with Partial and Controlled Cribbing Encoders

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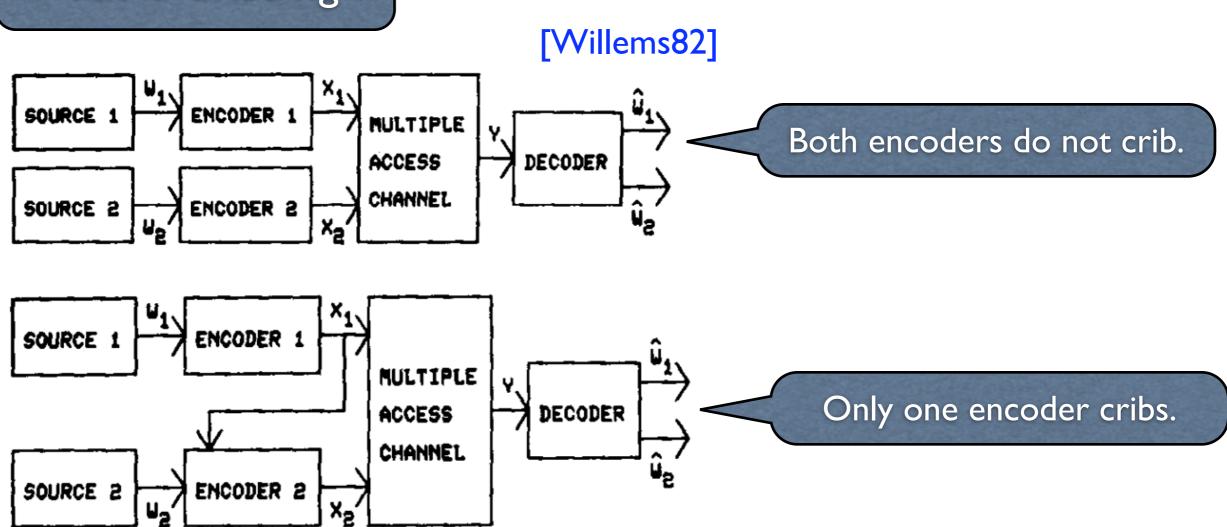
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ISIT, St. Petersburg, Russia August 4, 2011

# What is Cribbing?

# SOURCE 1 ENCODER 1 NULTIPLE ACCESS CHANNEL SOURCE 2 Up ENCODER 2 X2 CHANNEL Up DECODER 1 Up ENCODER 2 X2 CHANNEL Up DECODER 1 Up ENCODER 2 X2 CHANNEL Up DECODER 1 Up ENCODER 2 X2 CHANNEL Up DECODER 2 X2 CHANNEL UP DECODER

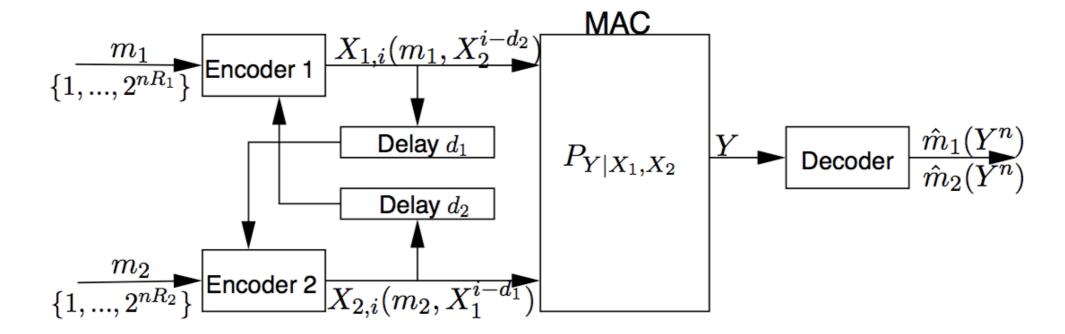
# What is Cribbing?



### What is Cribbing? [Willems82] ENCODER 1 SOURCE 1 MULTIPLE Both encoders do not crib. DECODER ACCESS CHANNEL ENCODER 2 SOURCE 2 ENCODER 1 SOURCE 1 MULTIPLE Only one encoder cribs. ACCESS DECODER CHANNEL ENCODER 2 SOURCE 2 x<sub>2</sub>/ ENCODER 1 SOURCE 1 MULTIPLE Both encoders crib. ACCESS DECODER CHANNEL SOURCE 2 ENCODER 2

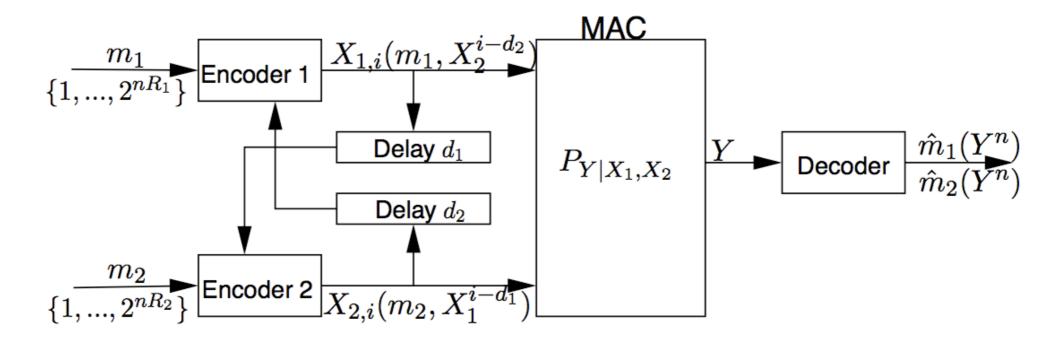
# What is Cribbing?

Each encoder knows the output of other encoder with some fixed delay [Willems82]



# What is Cribbing?

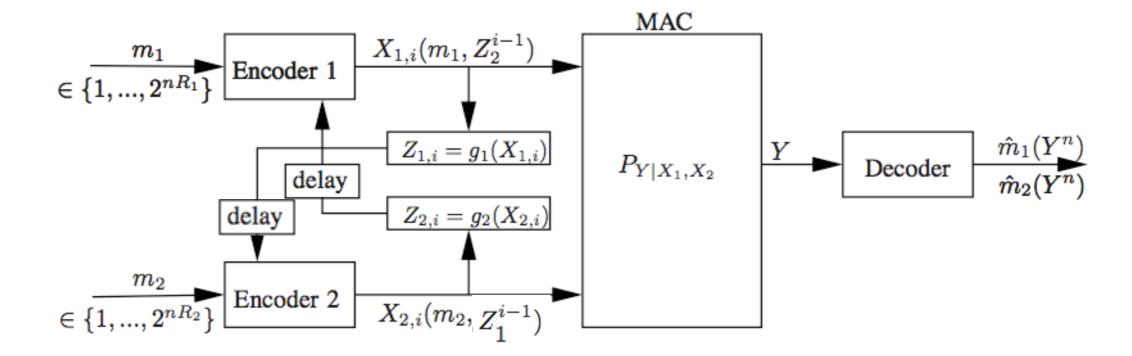
Each encoder knows the output of other encoder with some fixed delay [Willems82]



- Motivation : Cognitive Radio, Cooperation, Relay.
- Cribbing with State [BrossLapidoth 10]
- Interference Channel with Cribbing Encoder [BrossSteinbergTinguely 10]
- Trivial for Gaussian [Willems05]

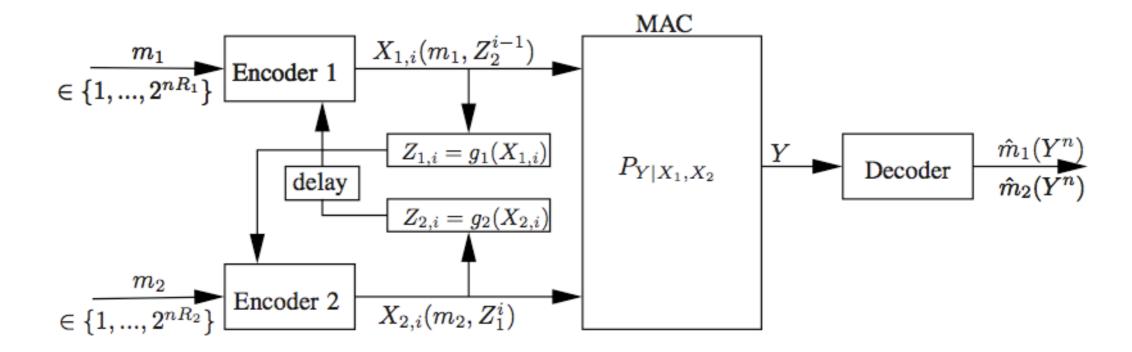
# Partial (deterministic-function) Cribbing

Case A: The cribbing at both encoders is strictly causal.



# Partial (deterministic-function) Cribbing

Case B: The cribbing at one encoder is strictly causal and at other encoder is causal.



### Capacity Region $\mathcal{R}_A$

$$\mathcal{R}_{A} = \left\{ \begin{array}{l} R_{1} \leq H(Z_{1}|U) + I(X_{1};Y|X_{2},Z_{1},U), \\ R_{2} \leq H(Z_{2}|U) + I(X_{2};Y|X_{1},Z_{2},U), \\ R_{1} + R_{2} \leq I(X_{1},X_{2};Y|U,Z_{1},Z_{2}) + H(Z_{1},Z_{2}|U), \\ R_{1} + R_{2} \leq I(X_{1},X_{2};Y), \text{ for } \\ P(u)P(x_{1},z_{1}|u)P(x_{2},z_{2}|u)P(y|x_{1},x_{2}). \end{array} \right\}$$

### Capacity Region $\mathcal{R}_A$

$$\mathcal{R}_{A} = \left\{ \begin{array}{l} R_{1} \leq H(Z_{1}|U) + I(X_{1};Y|X_{2},Z_{1},U), \\ R_{2} \leq H(Z_{2}|U) + I(X_{2};Y|X_{1},Z_{2},U), \\ R_{1} + R_{2} \leq I(X_{1},X_{2};Y|U,Z_{1},Z_{2}) + H(Z_{1},Z_{2}|U), \\ R_{1} + R_{2} \leq I(X_{1},X_{2};Y), \text{ for } \\ P(u)P(x_{1},z_{1}|u)P(x_{2},z_{2}|u)P(y|x_{1},x_{2}). \end{array} \right\}$$

# Mixed Strictly Causal and Causal Cribbing (Case B)

### Capacity Region $\mathcal{R}_B$

$$\mathcal{R}_{B} = \left\{ \begin{array}{l} R_{1} \leq H(Z_{1}|U) + I(X_{1};Y|X_{2},Z_{1},U), \\ R_{2} \leq H(Z_{2}|U) + I(X_{2};Y|X_{1},Z_{2},U), \\ R_{1} + R_{2} \leq I(X_{1},X_{2};Y|U,Z_{1},Z_{2}) + H(Z_{1},Z_{2}|U), \\ R_{1} + R_{2} \leq I(X_{1},X_{2};Y), \text{ for } \\ P(u)P(x_{1},z_{1}|u)P(x_{2},z_{2}|z_{1},u)P(y|x_{1},x_{2}). \end{array} \right\}$$

### Capacity Region

$$\mathcal{R}_{A} = \left\{ \begin{array}{l} R_{1} \leq H(Z_{1}|U) + I(X_{1};Y|X_{2},Z_{1},U), \\ R_{2} \leq H(Z_{2}|U) + I(X_{2};Y|X_{1},Z_{2},U), \\ R_{1} + R_{2} \leq I(X_{1},X_{2};Y|U,Z_{1},Z_{2}) + H(Z_{1},Z_{2}|U), \\ R_{1} + R_{2} \leq I(X_{1},X_{2};Y), \text{ for } \\ P(u)P(x_{1},z_{1}|u)P(x_{2},z_{2}|u)P(y|x_{1},x_{2}). \end{array} \right\}$$

$$Z_1 = \phi, Z_2 = \phi$$

$$\mathcal{R}_{nc} = \left\{ \begin{array}{l} R_1 \leq I(X_1; Y | X_2), \\ R_2 \leq I(X_2; Y | X_1), \\ R_1 + R_2 \leq I(X_1, X_2; Y), \text{ for } \\ P(x_1) P(x_2) P(y | x_1, x_2). \end{array} \right\}$$

MAC with no cooperation

### Capacity Region

$$\mathcal{R}_{A} = \left\{ \begin{array}{l} R_{1} \leq H(Z_{1}|U) + I(X_{1};Y|X_{2},Z_{1},U), \\ R_{2} \leq H(Z_{2}|U) + I(X_{2};Y|X_{1},Z_{2},U), \\ R_{1} + R_{2} \leq I(X_{1},X_{2};Y|U,Z_{1},Z_{2}) + H(Z_{1},Z_{2}|U), \\ R_{1} + R_{2} \leq I(X_{1},X_{2};Y), \text{ for } \\ P(u)P(x_{1},z_{1}|u)P(x_{2},z_{2}|u)P(y|x_{1},x_{2}). \end{array} \right\}$$

$$Z_1 = \phi, Z_2 = \phi$$

$$\mathcal{R}_{nc} = \begin{cases} R_1 \leq I(X_1; Y | X_2), \\ R_2 \leq I(X_2; Y | X_1), \\ R_1 + R_2 \leq I(X_1, X_2; Y), \text{ for } \\ P(x_1)P(x_2)P(y | x_1, x_2). \end{cases}$$

$$Z_1 = X_1, Z_2 = X_2$$

$$\mathcal{R}_{nc} = \left\{ \begin{array}{l} R_1 \leq I(X_1; Y | X_2), \\ R_2 \leq I(X_2; Y | X_1), \\ R_1 + R_2 \leq I(X_1, X_2; Y), \text{ for } \\ P(x_1) P(x_2) P(y | x_1, x_2). \end{array} \right\} \qquad \mathcal{R}_c = \left\{ \begin{array}{l} R_1 \leq H(X_1 | U), \\ R_2 \leq H(X_2 | U), \\ R_1 + R_2 \leq I(X_1, X_2; Y), \text{ for } \\ P(u) P(x_1 | u) P(x_2 | u) P(y | x_1, x_2). \end{array} \right\}$$

MAC with no cooperation

MAC with perfect cribbing

# Achievability Outline: Coding Techniques Used

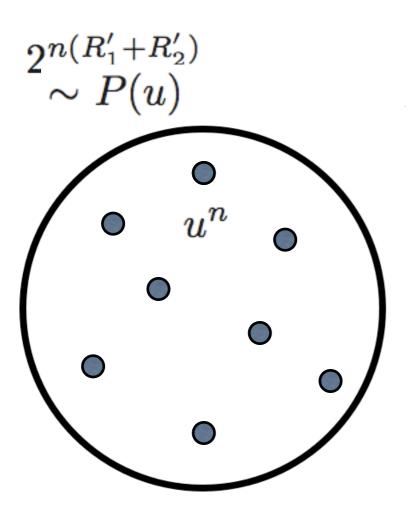
- Block Markov Coding.
- Superposition Coding.
- Shannon Strategies.
- Backward Decoding.
- Rate Splitting.

Divide a block of length Bn into B blocks of length n.

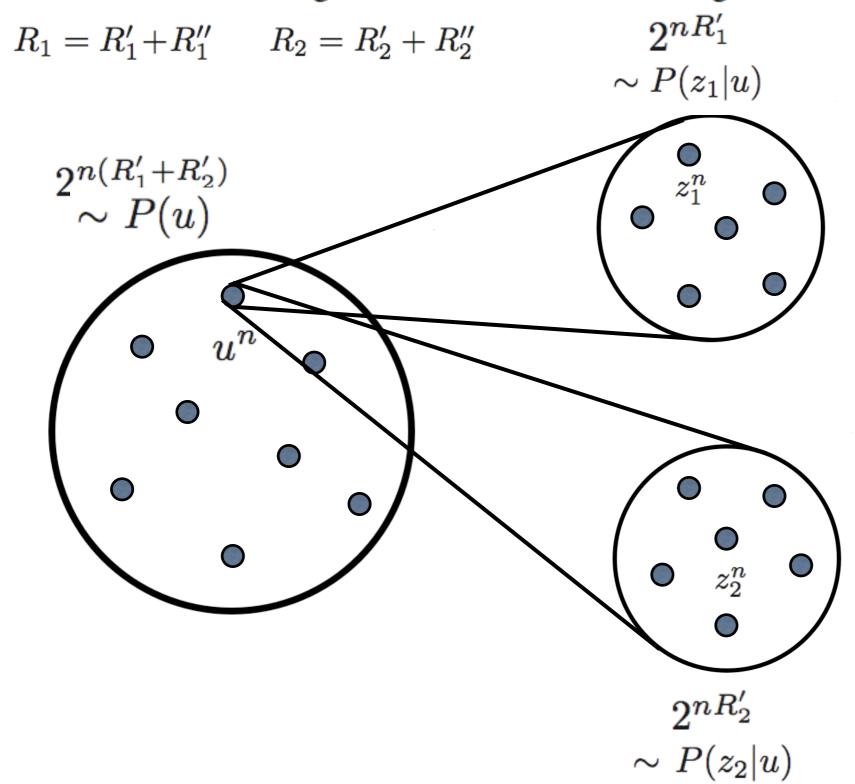
$$R_1 = R_1' + R_1''$$
  $R_2 = R_2' + R_2''$ 

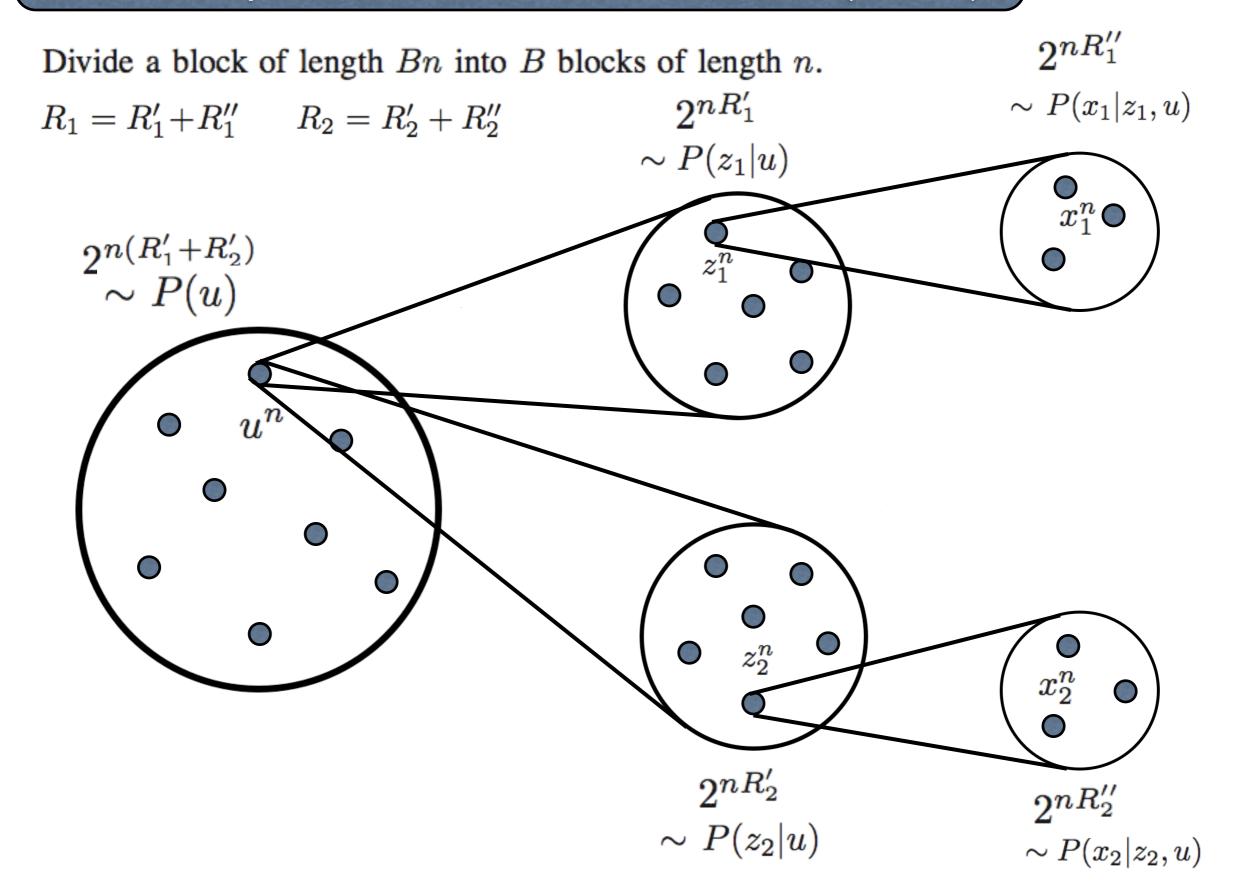
Divide a block of length Bn into B blocks of length n.

$$R_1 = R_1' + R_1''$$
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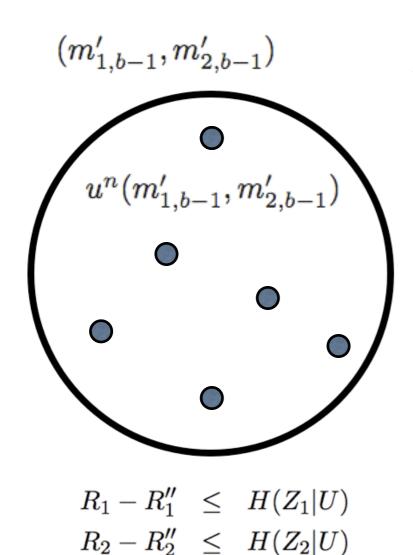
Divide a block of length Bn into B blocks of length n.



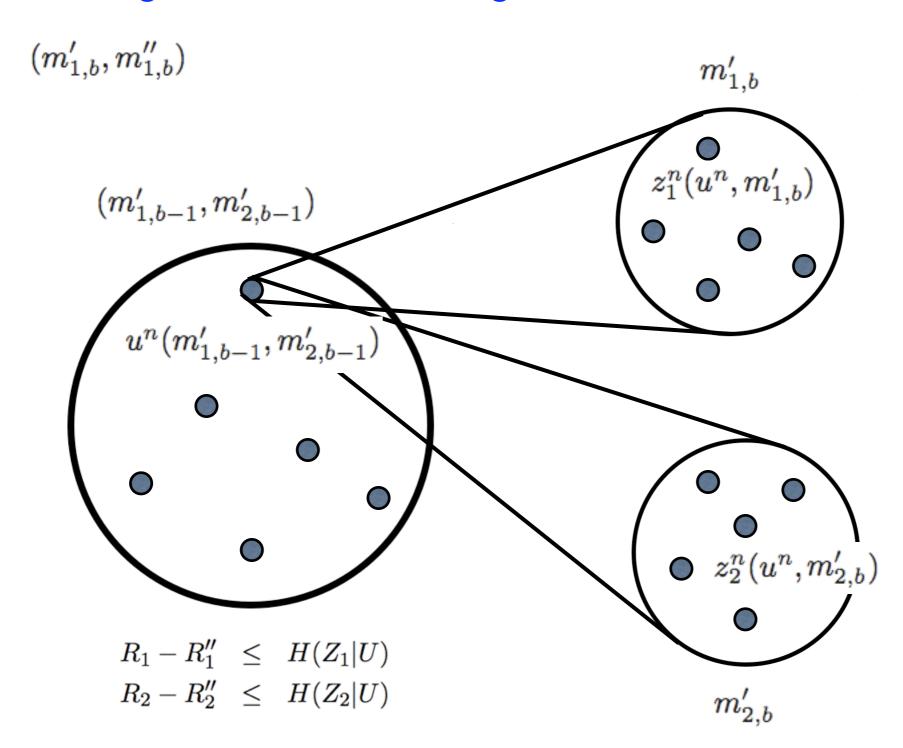


### **Encoding: Block Markov Coding**

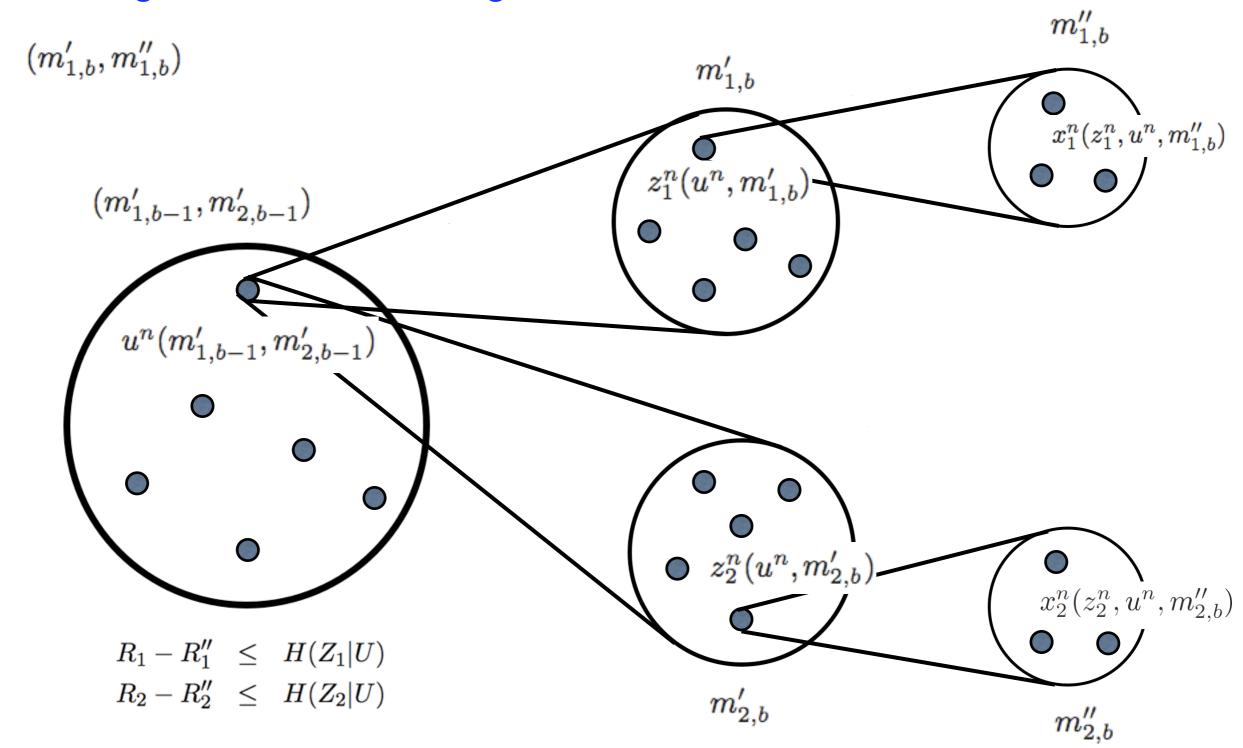
$$(m'_{1,b}, m''_{1,b})$$



### **Encoding: Block Markov Coding**



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### **Backward Decoding**

At block b,  $(m'_{1,b}, m'_{2,b})$  is already known

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At block b,  $(m'_{1,b}, m'_{2,b})$  is already known

at block b it looks for  $(\hat{m}'_{1,b-1}, \hat{m}'_{2,b-1})$ ,  $\hat{m}''_{1,b}$  and  $\hat{m}''_{2,b}$  for which

$$(u^n(\hat{m}'_{1,b-1},\hat{m}'_{2,b-1}),z_1^n(u^n,m'_{1,b}),z_2^n(u^n,m'_{2,b}),x_1^n(z_1^n,u^n,\hat{m}''_{1,b}),x_2^n(z_2^n,u^n,\hat{m}''_{2,b})$$

$$\in T_{\epsilon}^{(n)}(U, Z_1, Z_2, X_1, X_2, Y)$$

# Achievability Outline: Error Analysis (Case A)

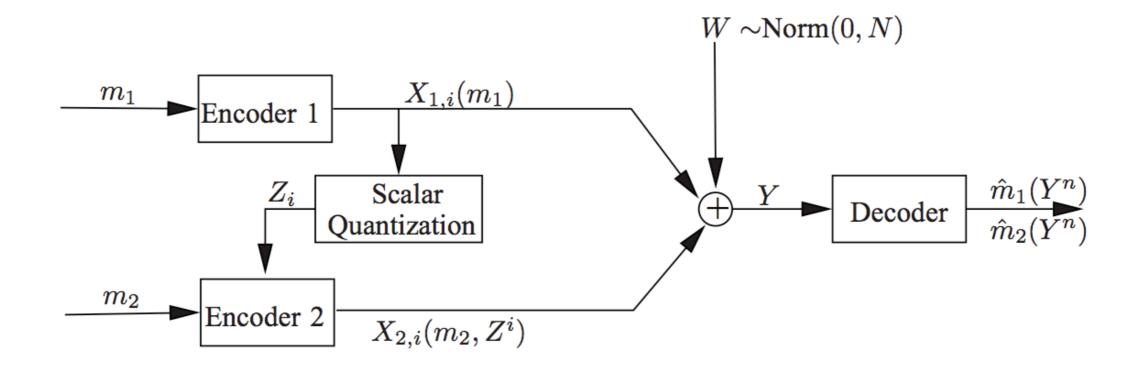
$$R_1 - R_1'' \le H(Z_1|U),$$
  
 $R_2 - R_2'' \le H(Z_2|U),$   
 $R_1'' \le I(X_1; Y|X_2, Z_1, U),$   
 $R_2'' \le I(X_2; Y|X_1, Z_2, U),$   
 $R_1'' + R_2'' \le I(X_1, X_2; Y|Z_1, Z_2, U),$   
 $R_1 + R_2 \le I(X_2, X_1; Y),$ 

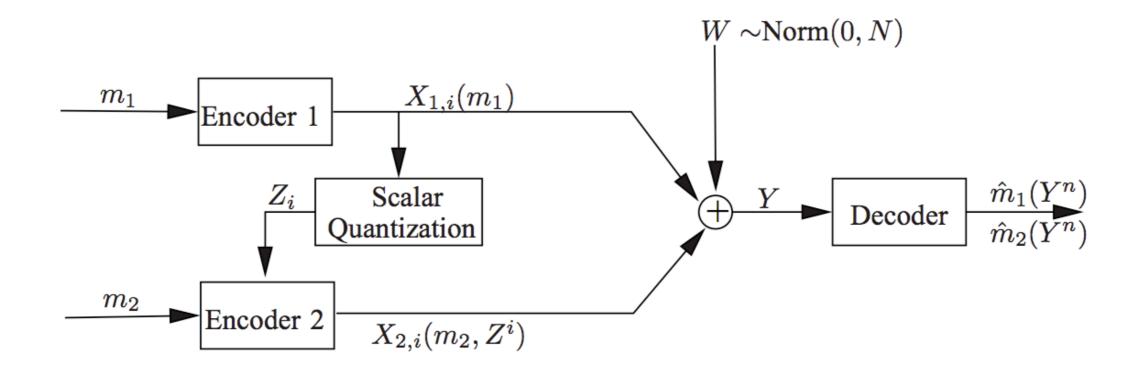
# Achievability Outline: Error Analysis (Case A)

$$R_1 - R_1'' \le H(Z_1|U),$$
  
 $R_2 - R_2'' \le H(Z_2|U),$   
 $R_1'' \le I(X_1; Y|X_2, Z_1, U),$   
 $R_2'' \le I(X_2; Y|X_1, Z_2, U),$   
 $R_1'' + R_2'' \le I(X_1, X_2; Y|Z_1, Z_2, U),$   
 $R_1 + R_2 \le I(X_2, X_1; Y),$ 

### Using Fourier-Motzkin elimination

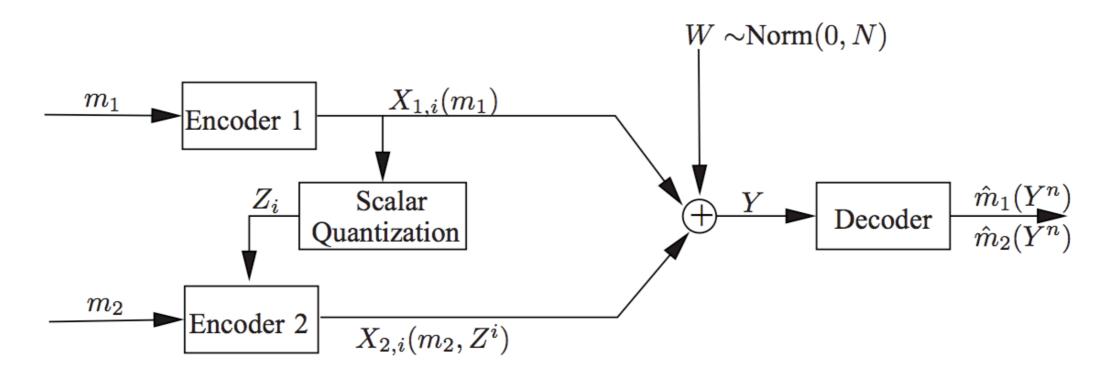
$$R_1 - H(Z_1|U) \le I(X_1; Y|X_2, Z_1, U),$$
 $R_2 - H(Z_2|U) \le I(X_2; Y|X_1, Z_2, U),$ 
 $R_1 - H(Z_1|U) + R_2 - H(Z_2|U) \le I(X_1, X_2; Y|Z_1, Z_2, U),$ 
 $R_1 + R_2 \le I(X_2, X_1; Y),$ 





$$\frac{1}{n} \sum_{i=1}^{n} E[X_{1,i}^2] \le P_1$$

$$\frac{1}{n} \sum_{i=1}^{n} E[X_{12i}^2] \le P_2$$

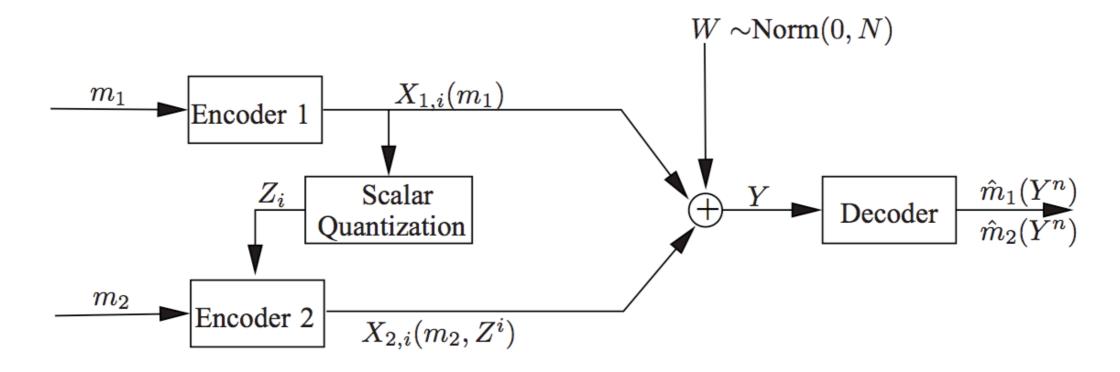


### No Cooperation

$$R_1 \leq \frac{1}{2} \log \left( 1 + \frac{P_1}{N} \right)$$

$$R_2 \leq \frac{1}{2} \log \left( 1 + \frac{P_2}{N} \right)$$

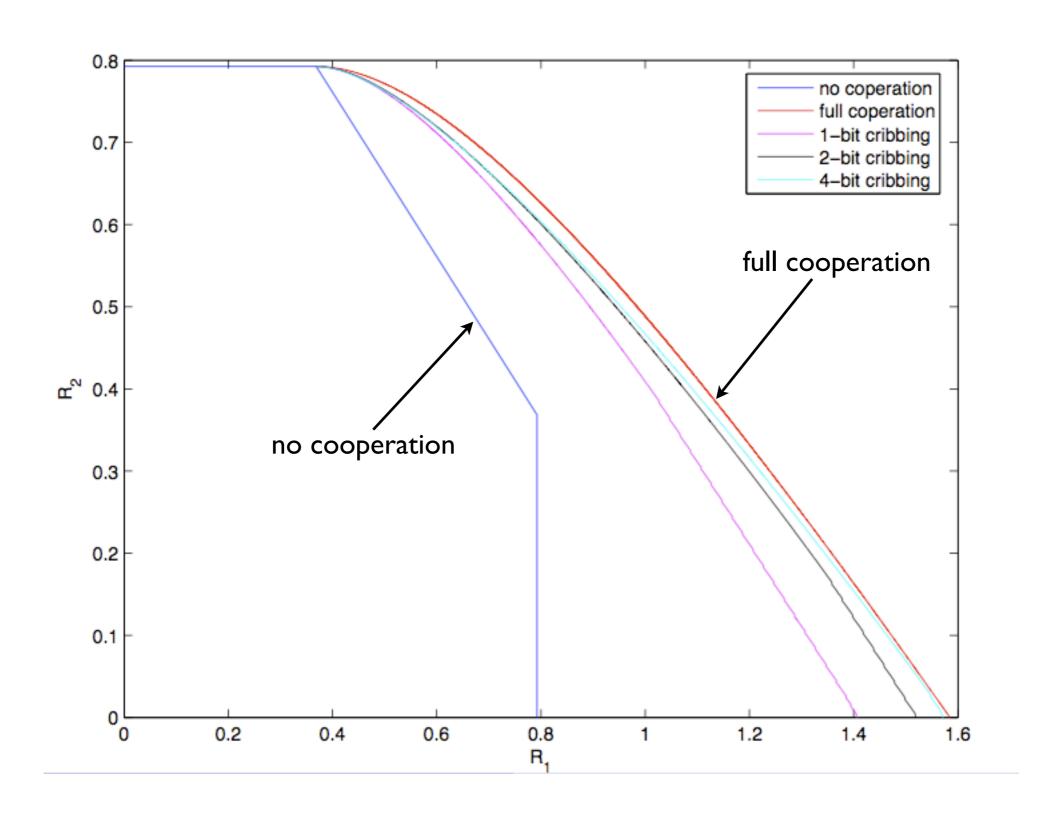
$$R_1 + R_2 \leq \frac{1}{2} \log \left( 1 + \frac{P_1 + P_2}{N} \right)$$



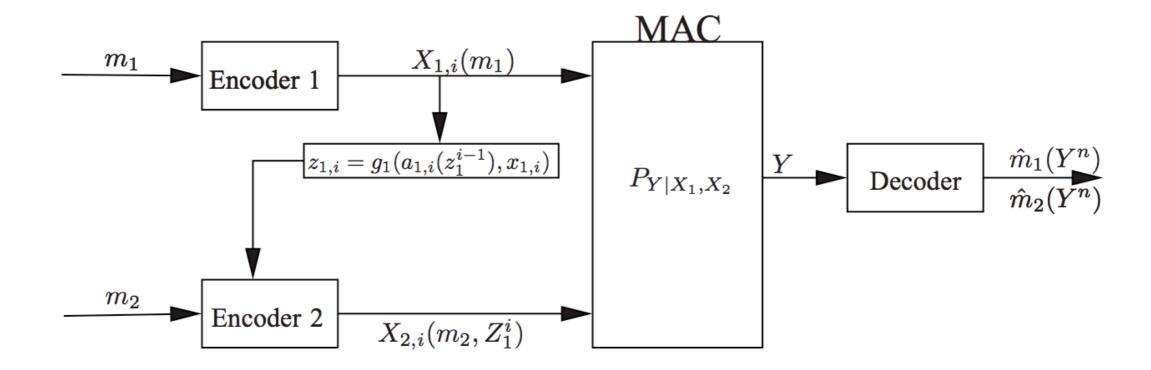
### **Full Cooperation**

the capacity is the union over  $0 \le \rho \le 1$  of the regions

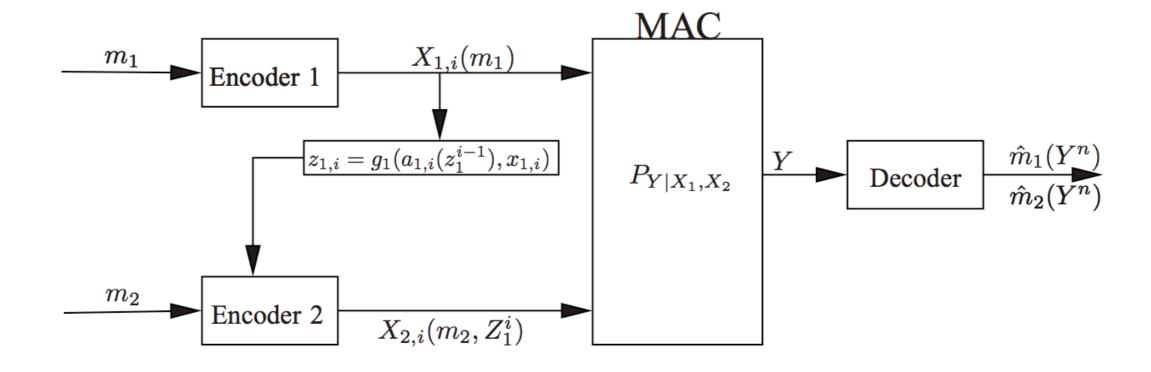
$$R_2 \le \frac{1}{2} \log \left( 1 + \frac{P_2}{N} (1 - \rho^2) \right)$$
 $R_1 + R_2 \le \frac{1}{2} \log \left( 1 + \frac{P_1 + 2\rho\sqrt{P_1P_2} + P_2}{N} \right)$ 



# Controlled Cribbing

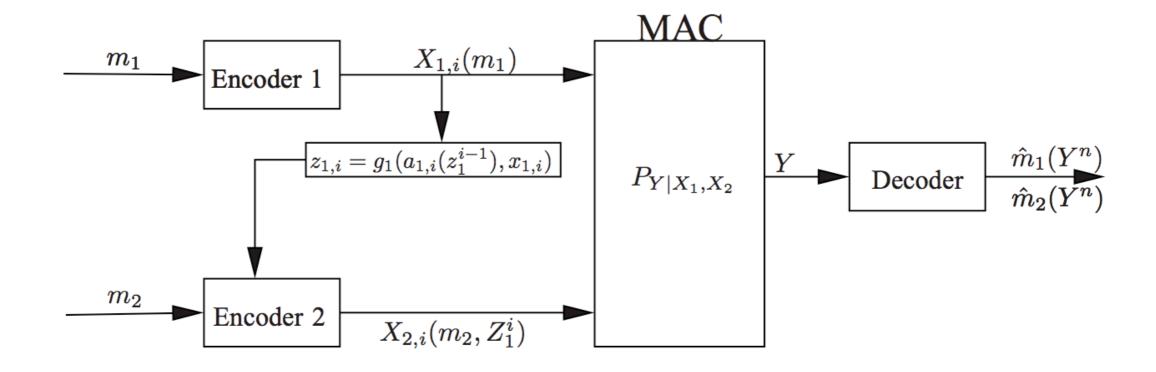


# Controlled Cribbing



Case A 
$$f_{2,i}: \{1,...,2^{nR_2}\} \times \mathcal{Z}_1^{i-1} \mapsto X_{2,i},$$
  
Case B  $f_{2,i}: \{1,...,2^{nR_2}\} \times \mathcal{Z}_1^i \mapsto X_{2,i},$ 

# Controlled Cribbing



$$\frac{1}{n} \sum_{i=1}^{n} E[\Lambda_1(A_{1,i})] \leq \Gamma_1$$

# Case A: Strictly Causal Controlled Cribbing

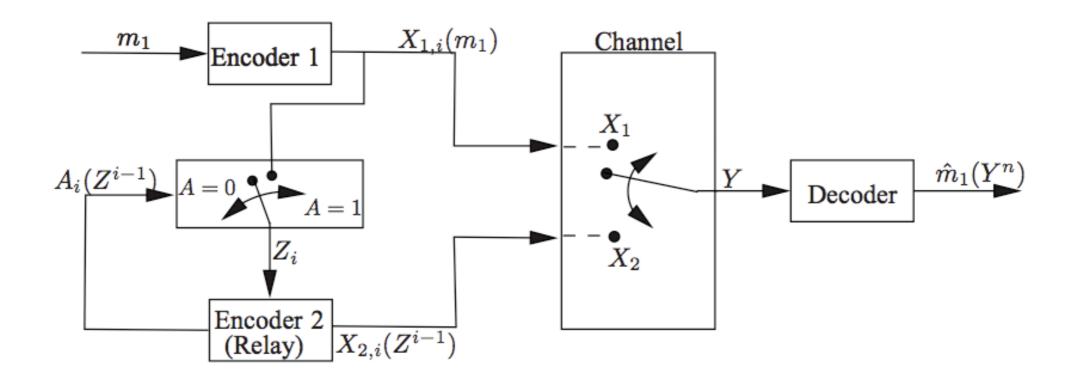
$$\mathcal{R}_{A}^{a} = \begin{cases} R_{1} \leq H(Z_{1}|U,A_{1}) + I(X_{1};Y|X_{2},Z_{1},U,A_{1}), \\ R_{2} \leq I(X_{2};Y|X_{1},U,A_{1}), \\ R_{1} + R_{2} \leq I(X_{1},X_{2};Y|U,A_{1},Z_{1}) + H(Z_{1}|U,A_{1}), \\ R_{1} + R_{2} \leq I(X_{1},X_{2};Y), \text{ for } \\ P(u,a_{1})P(x_{1},z_{1}|u,a_{1})P(x_{2}|u,a_{1})P(y|x_{1},x_{2}) \\ \text{s.t. } E[\Lambda_{1}(A_{1})] \leq \Gamma_{1}. \end{cases}$$

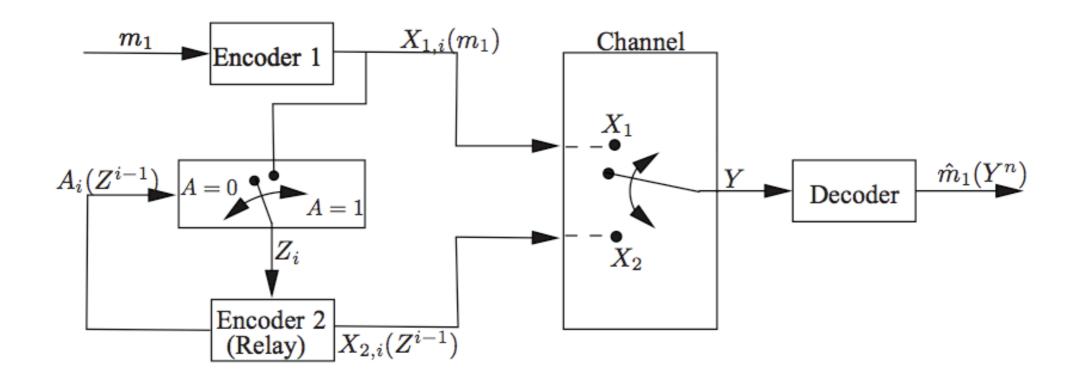
# Case A: Strictly Causal Controlled Cribbing

$$\mathcal{R}_A^a = \\ \begin{cases} R_1 \leq H(Z_1|U,A_1) + I(X_1;Y|X_2,Z_1,U,A_1), \\ R_2 \leq I(X_2;Y|X_1,U,A_1), \\ R_1 + R_2 \leq I(X_1,X_2;Y|U,A_1,Z_1) + H(Z_1|U,A_1), \\ R_1 + R_2 \leq I(X_1,X_2;Y), \text{ for } \\ P(u,a_1)P(x_1,z_1|u,a_1)P(x_2|u,a_1)P(y|x_1,x_2) \\ \text{s.t. } E[\Lambda_1(A_1)] \leq \Gamma_1. \end{cases}$$

# Case B: Causal Controlled Cribbing

$$\mathcal{R}^{a}_{B} = \begin{cases} R_{1} \leq H(Z_{1}|U,A_{1}) + I(X_{1};Y|X_{2},Z_{1},U,A_{1}), \\ R_{2} \leq I(X_{2};Y|X_{1},U,A_{1}), \\ R_{1} + R_{2} \leq I(X_{1},X_{2};Y|U,A_{1},Z_{1}) + H(Z_{1}|U,A_{1}), \\ R_{1} + R_{2} \leq I(X_{1},X_{2};Y), \text{ for } \\ P(u,a_{1})P(x_{1},z_{1}|u,a_{1})P(x_{2}|z_{1},u,a_{1})P(y|x_{1},x_{2}) \\ \text{s.t. } E[\Lambda_{1}(A_{1})] \leq \Gamma_{1} \end{cases}$$



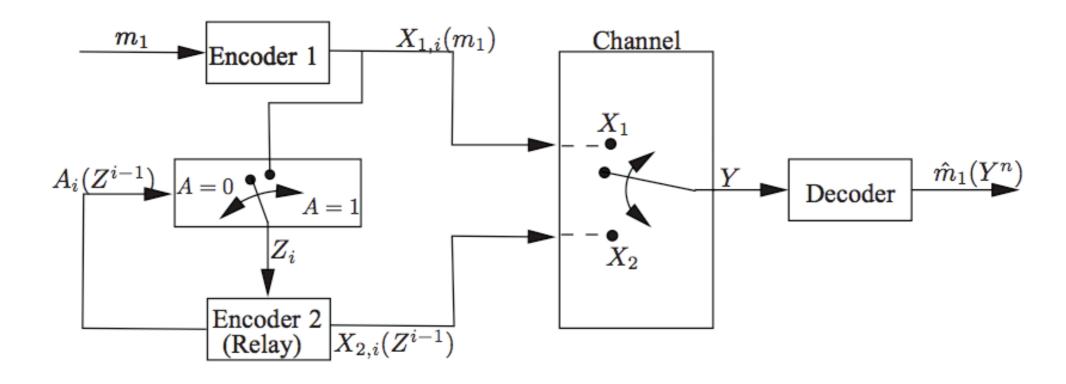


If  $A_i = 1$ , then  $Z_i = X_i$ , and otherwise  $Z_i$  is a constant.

$$\frac{1}{n} \sum_{i=1}^{n} E[A_i] \leq \Gamma$$

$$R_2 = 0$$

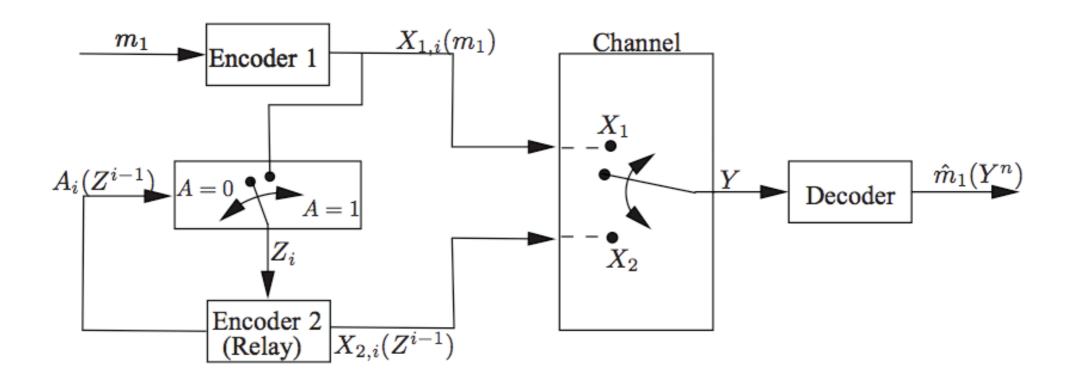
### Capacity Region



delay in the cribbing (Case A) [ElGamalAref82]

$$R_1 = \max_{P_{X_1,X_2,A}: E[c(A)] \leq \Gamma} \min\{H(Z|X_2,A) + I(X_1;Y|X_2,Z_1,A), I(Y;X_1,X_2)\}$$

### Capacity Region



delay in the cribbing (Case A) [ElGamalAref82]

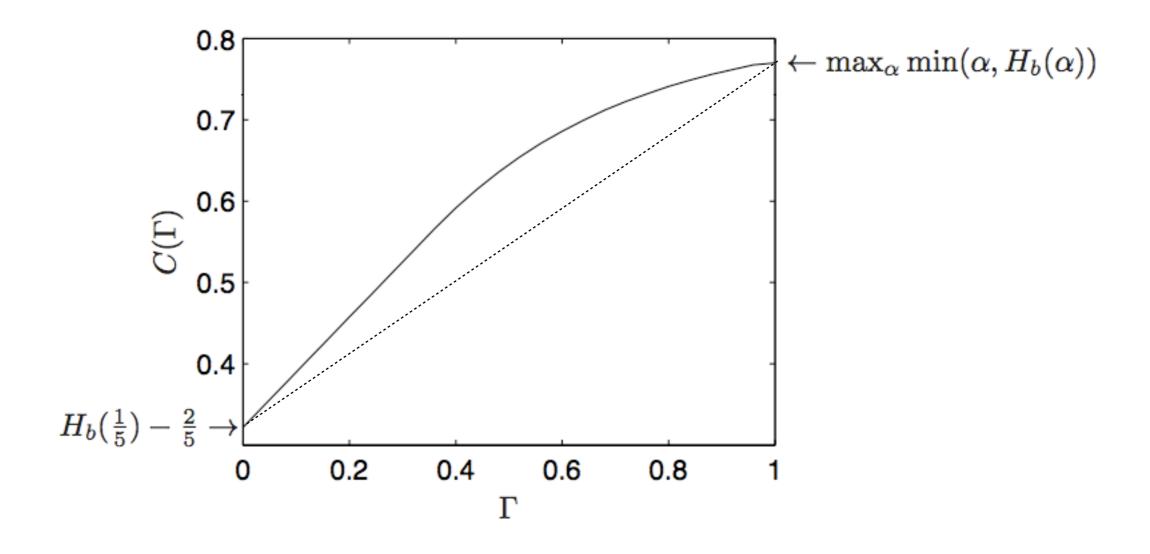
$$R_1 = \max_{P_{X_1,X_2,A}: E[c(A)] \leq \Gamma} \min\{H(Z|X_2,A) + I(X_1;Y|X_2,Z_1,A), I(Y;X_1,X_2)\}$$

no delay in the cribbing (Case B), i.e.,  $X_{2,i}(Z^i)$  [ElGamalHassanpourMammen07]

$$R_1 = \max_{P_{U,X_1,A}P_{X_2|U,Z,A}: E[c(A)] \leq \Gamma} \min\{H(Z|U,A) + I(X_1;Y|X_2,Z,U,A), I(Y;X_1,X_2)\}.$$

### Capacity Region

### Case A



# Summary

- Cribbing is an important concept in cognitive radios, cooperation and relaying.
- Capacity region of deterministic using : block markov codes, strategies, superposition coding, backward decoding and rate splitting
- We see that for AWGN MAC with causal quantized cribbing, few bits are enough.
- Controlled Cribbing.

# Future Work

- Non-causal Partial (deterministic) cribbing.
- Controlled Cribbing with actions dependent on messages, i.e.,  $a_{1,i}(z_1^{i-1},m_1)$

Thanks !!!
Questions?